

### From Multimodal LLM to Human-level Al

Architecture, Modality, Function, Instruction, Hallucination, Evaluation, Reasoning and Beyond



https://mllm2024.github.io/ACM-MM2024/























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# MLLM Functionality& Advance

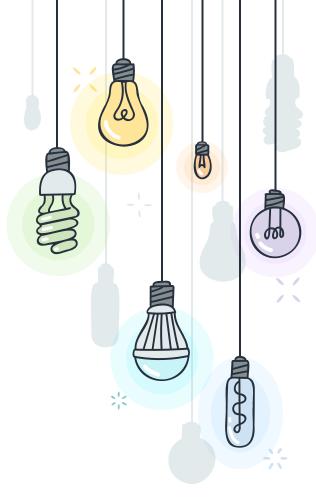


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ByteDance/Tiktok, Singapore

https://lxtgh.github.io/



## MLLM Functionality& Advance

### + Fine-Grained MLLM Design

- × Overview
- × With Visual Grounding.
- × With Visual Segmentation.
- × Video and 3D Fine-Grained MLLM.

### + Advanced MLLM Design

- × Overview
- × Unified Architecture Designs.
- × MLLM For Long Video Analysis.
- × MLLM With MOE Design.

# MLLM Functionality& Advance

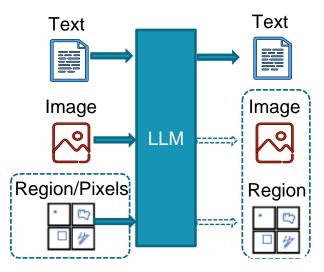
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### Overview and Concepts

#### **Fine-Grained MLLM:**

- 1, Region-level or Pixel-level visual prompts as inputs and outputs.
- 2, Aims at understanding multi-granularity concepts in image/video/3D.
- 3, Enhance the interactive features in MLLM. This is important in the real product.



### **Motivation**

#### Why We need Fine-grained MLLM?

#### **New Features:**

- refer to specific regions/objects/masks and perform chat.
- understanding and reasoning region and pixel.

#### **New Applications:**

- VR / AR application.
- Medical image analysis.

#### New Model Designs:

- How to avoid hallucination.
- How to balance chat and localization ability.

### Overview of Fine-grained Models Before LLM

Visual Grounding

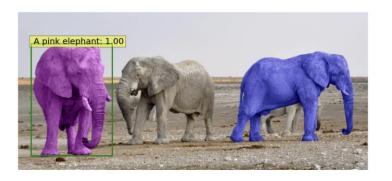
Referring Segmentation

Visual Segmentation

Video/3D Referring Segmentation

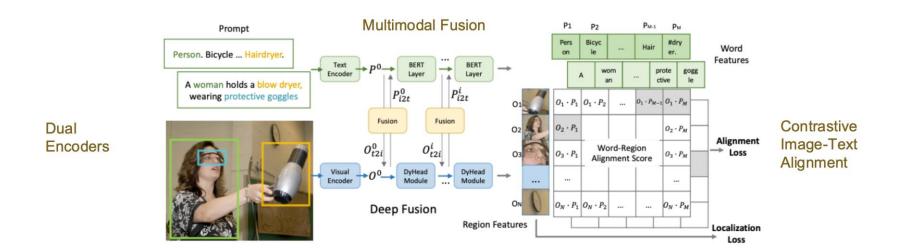
Visual Prompting.

- Various tasks that driven by language.
- Most works come from **vision** community.
- **Dual** branches designs by connecting language model and vision model (detector or segmenter)





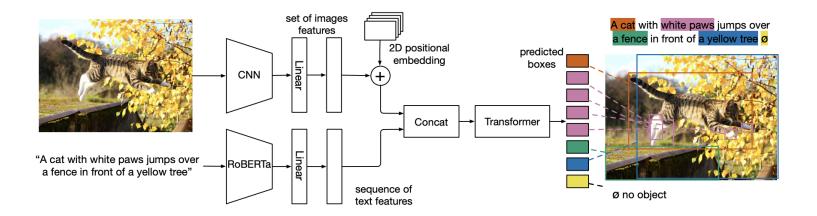
### Overview of Fine-grained Models Before LLM



GLIP: Grounded Language-Image Pre-training. 2022.

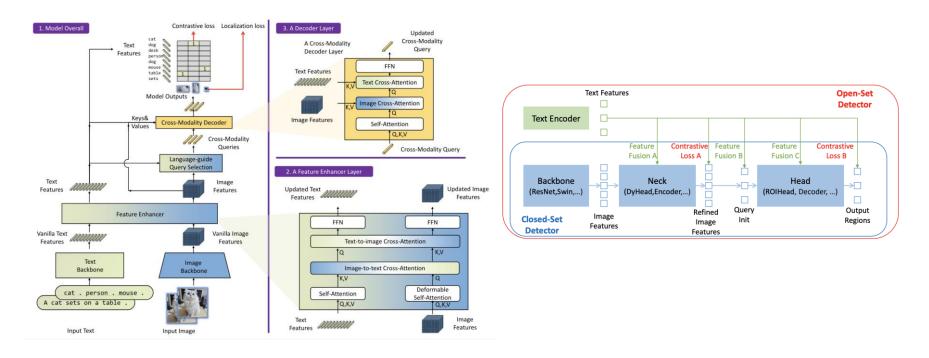


### Overview of Fine-grained Models Before LLM

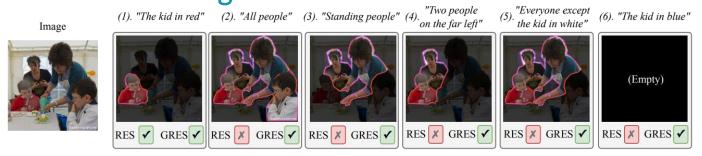


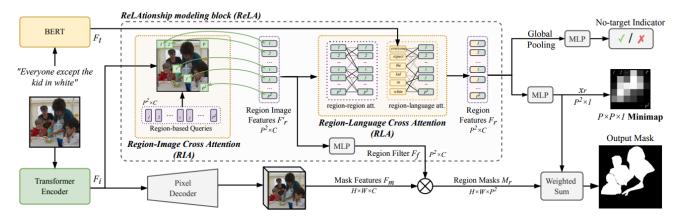


### Overview of Fine-grained Models Before LLM



### Overview of Fine-grained Models Before LLM



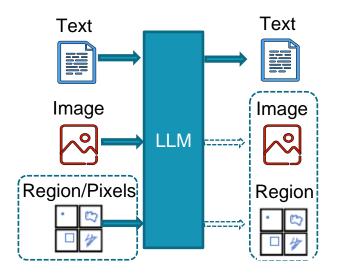


### Overview

- GPT4RoI
- NFxT-Chat
- MiniGPT-v2
- Shikra
- Kosmos-2
- GLaMM
- LISA
- DetGPT
- Osprey
- PixelLM
- OMG-LLaVA
- VITRON



Users input an image (potentially specifying a region), and the LLM outputs content based on its understanding, grounding the visual content to specific pixellevel regions of the image.



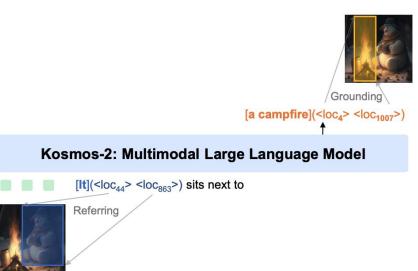
- [1] GPT4RoI: Instruction Tuning Large Language Model on Region-of-Interest. 2023
- [2] NExT-Chat: An LMM for Chat, Detection and Segmentation. 2023
- [3] MiniGPT-v2: large language model as a unified interface for vision-language multi-task learning. 2023
- [4] Osprey: Pixel Understanding with Visual Instruction Tuning. 2023
- [5] GLaMM: Pixel Grounding Large Multimodal Model. 2023
- [6] Kosmos-2: Grounding Multimodal Large Language Models to the World. 2023
- [7] DetGPT: Detect What You Need via Reasoning. 2023
- [8] PixelLM: Pixel Reasoning with Large Multimodal Model. 2023
- [9] Lisa: Reasoning segmentation via large language model. 2023
- [10] Shikra: Unleashing Multimodal LLM's Referential Dialogue Magic. 2023

### + Fine-Grained MLLM Design

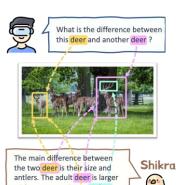
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### With Visual Grounding.

Kosmos-2:



#### Shikra:



The main difference between the two deer is their size and antlers. The adult deer is larger with more prominent antlers, while the younger deer is smaller with no visible antlers.



How is the person in the picture feeling[0.610,0.251,0.825, 0.829]? How did you find out?

The person in the picture [0.610,0.251,0.825,0.829] is feeling surprised and happy. We can infer this from the fact that she is covering her face with her hands [0.612,0.352,0.690,0.444] while looking at the man [0.216,0.223,0.558,0.832] offering her a bunch of red roses [0.412,0.390,0.580,0.756].

What is unusual about this image? give coordinates [xmin,ymin,xmax,ymax] for the items you reference.

The unusual aspect of this image is the man [0.392,0.254,0.652, 0.530] standing on top of the ironing board [0.330, 0.320,0.665, 0.756] in the back of the yellow SUV [0.452,0.384,0.998,0.738]. The scene is unusual and unexpected, as one would typically not expect to see someone ironing clothes while standing on top of the car.





What is this man [0.171,0.330,0.650,0.779] scared of?

The man [0.171,0.330,0.650,0.779] is scared of the chicken [0.620,0.219,0.996,0.659] that is flying towards him.

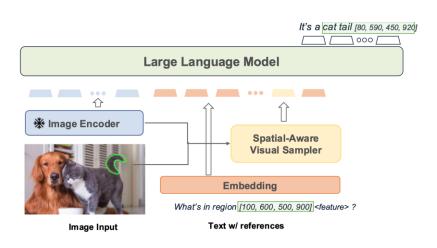
Can you explain this meme? give coordinates [xmin,ymin, xmax,ymax] for the items you reference.

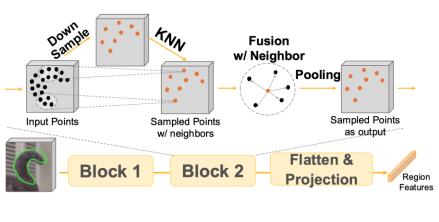
In this image, a person [0.002,0.490,0.208,0.832] is holding a water-spraying tool [0.180,0.546,0.408,0.830] and is pointing it at a filed wall [0.002,0.168,0.998,0.830]. The water is dripping from the wall in the shape of the question mark [0.432,0.422,0.626,0.658]. This creates an interesting visual effect, as the question mark appears on the wall while the water is sprayed to resemble the question mark.

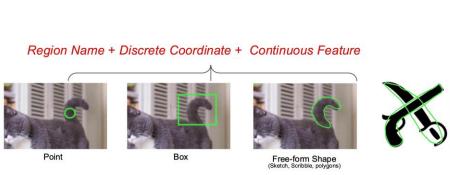


### With Visual Grounding.

**Ferret** 





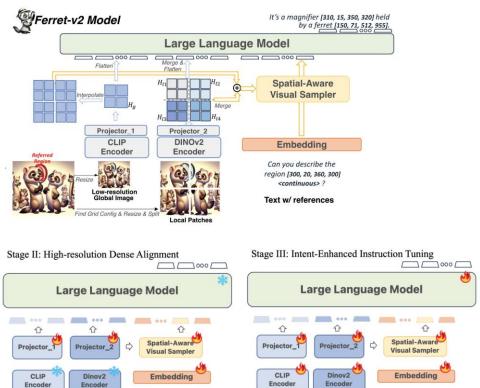


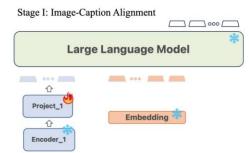
Ferret: Refer and Ground Anything Anywhere at Any Granularity, arxiv-2023.

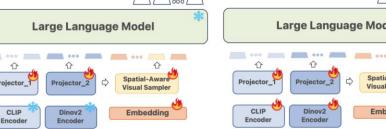


### With Visual Grounding.

Ferret-v2



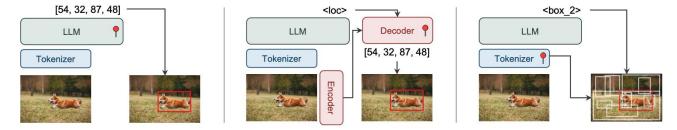


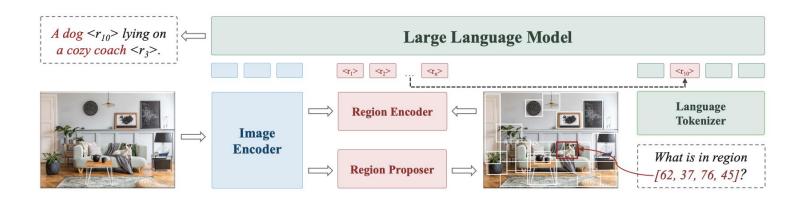




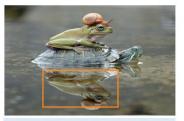
### With Visual Grounding.

Groma:





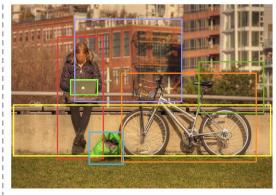
### With Visual Grounding.



- Locate the the reflection of the frog.
- It's located at <region>.



- Please give a brief description of <region>.
  - A large dinosaur skeleton.



[grounding] Is it safe to drive like this?



It's not advisable. The man is holding a cup in one hand and talking on the phone, which means he's not using both hands on the steering wheel. This could be a distraction and increase the risk of an accident.

- [grounding] Can you describe this image in details?
  - In this image, we see a woman sitting on a concrete bench working on her laptop. She's surrounded by a green bag and a white bicycle that's leaning against the bench. Behind her, there's a large brick building and a tree.

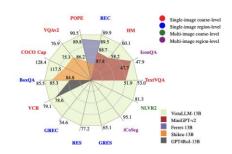
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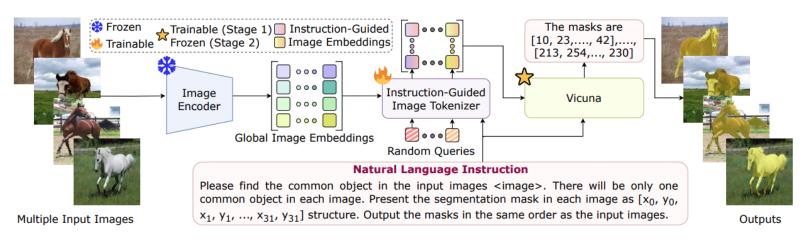
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With Visual Segmentation.

VistaLLM





Jack of All Tasks, Master of Many: Designing General-purpose Coarse-to-Fine Vision-Language Model, arixv-2023.

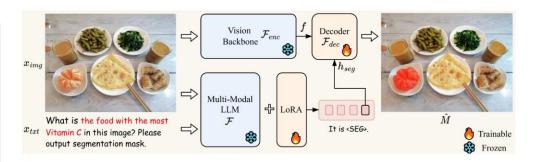


### With Visual Segmentation.

LISA: Large Language Instructed Segmentation Assistant







- USER: <IMAGE> Can you segment the tyre that does not touch the ground in this image? ASSISTANT: Sure, it
- is <SEG>.





USER: <IMAGE> There are two washing machines as shown in the picture. If I need to do laundry, where in the picture would I put the clothes? Please output segmentation mask. ASSISTANT: <SEG>.





- USER: <IMAGE> Can you segment the food that tastes not spicy in this
- ASSISTANT: <SEG>





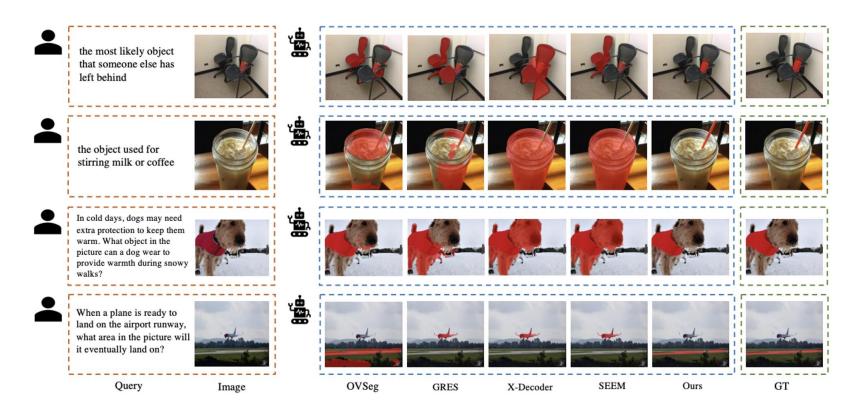
USER: <IMAGE> What is the place where the driver can observe the speed in this image? Please output segmentation mask. ASSISTANT: <SEG>.





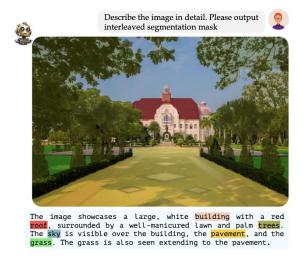


#### With Visual Segmentation.





#### With Visual Segmentation.



Method	Image	Inpu	ıt / Output	Region	Pixel-Wise	Multi-turn	End-End
Medica	mage	Region	Multi-Region	Enc. / Dec.	Grounding	Conversation	Model
MM-REACT (arXiv-23) [51]	1	X/X	X/X	×/×	×	1	X
LLaVA (NeurIPS-23) [29]	1	X/X	×/×	X/X	X	✓	1
miniGPT4 (arXiv-23) [61]	1	X/X	X/X	X/X	X	✓	1
mPLUG-OWL (arXiv-23) [52]	1	X/X	X/X	X/X	X	✓	1
LLaMA-Adapter v2 (arXiv-23) [8]	1	X/X	X/X	X/X	X	✓	1
Otter (arXiv-23) [22]	1	X/X	×/×	X/X	×	×	1
Instruct-BLIP (arXiv-23) [6]	1	X/X	X/X	X/X	X	✓	1
InternGPT (arXiv-23) [31]	1	V/X	X/X	X/X	X	<b>/</b>	X
Bubo-GPT (arXiv-23) [59]	1	× /✓	× /√	X/X	X	✓	X
Vision-LLM (arXiv-23) [44]	1	XIV	<b>X</b> / <b>V</b>	X/X	×	×	<b>/</b>
Det-GPT (arXiv-23) [36]	1	111	111	X/X	X	✓	1
Shikra (arXiv-23) [5]	1	111	×/×	X/X	X	X	1
Kosmos-2 (arXiv-23) [35]	1	111	111	X/X	X	X	1
GPT4RoI (arXiv-23) [57]	1	VIX	<b>√</b> / <b>×</b>	<b>√/</b> ×	X	· · · · · · · · · · · · · · · · · · ·	<b>/</b>
ASM (arXiv-23) [45]	1	✓ / ×	X/X	√ / ×	X	X	✓
LISA (arXiv-23) [21]	1	× / 🗸	X/X	<b>X</b> / 🗸	✓	X	1
GLaMM (ours)	1	111	111	111	✓	1	✓



#### With Visual Segmentation.

#### Objects and Attributes

- 1 dog, pub dog, a brown and white dog
- 2 dog collar, black color, chain collar
- 3 bell, cowbell
- 4 steps, stairs, the steps of a building
- 5 sack, a large white bag with black writing

#### Relationships and Landmarks

A dog sitting on the steps

A large brown dog wearing a chain collar Cowbell attached to dog collar

Landmarks: Outdoor - Urban Landscape



Objects =	pub dog 1	dog collar 2	cowbell 3	steps 4	sack 5
Groups	pub dog 1	Foreground dog collar 2	cowbell 3	Midground steps 4	Background sack 5
Relations =	A dog 1 sitti	ng on the steps A large brow	Cow	rbell 3 attached to chain collar 2	o dog collar 2
Relations		white dog sitting dog with a cha		ng on the steps of	a building.
l andmark =		Outdoor Sce	ne Urb	an Landscape	

C-----1-

#### Dense Grounded Caption

A large brown dog is sitting on the steps of a building. It is wearing a black chain dog collar. The collar has a cowbell attached to it. There is a bag in the background with black writings on it.

#### Extra Context

Dogs, especially pugs and bulldogs, have been a part of human families for thousands of years, serving as loyal companions. They have been bred for specific traits, making them popular pets. Dogs have been trained for various tasks, including assisting people with disabilities and serving as search and rescue animals. Dog collars, often bearing identification tags, are essential for keeping pets safe and ensuring they can be returned home if lost. Cowbells, once used to signal the arrival of a cow, have been repurposed as dog collars, providing a distinct sound to help locate a dog if it wanders off. In outdoor urban landscape, dogs are often found sitting on steps, as they may choose to rest in spots that offer a good view of their surroundings.

Level-1	Level-2	Level-3	Level-4
Object locatlization and attributes  Image Tagging and Object Detection  Open Vocabulary Detection  Region Attribute Detection	Relationships Short Captions and Phrase extraction Grounding expression Landmarks	Scene Graph & Dense Captioning Hierarchical Scene Graph In-contex Learning with LLM Verification Pipeline	Extra Contextual Insights  Lanmark Details  History and Background  Precautionary Measures

Model		1	/alidatio	n Set		Test Set					
	M	C	AP50	mIoU	Recall	M	C	AP50	mIoU	Recall	
BuboGPT [59]	17.2	3.6	19.1	54.0	29.4	17.1	3.5	17.3	54.1	27.0	
Kosmos-2 [35]	16.1	27.6	17.1	55.6	28.3	15.8	27.2	17.2	56.8	29.0	
LISA* [21]	13.0	33.9	25.2	62.0	36.3	12.9	32.2	24.8	61.7	35.5	
GLaMM†	15.2	43.1	28.9	65.8	39.6	14.6	37.9	27.2	64.6	38.0	
GLaMM	16.2	47.2	30.8	66.3	41.8	15.8	43.5	29.2	65.6	40.8	

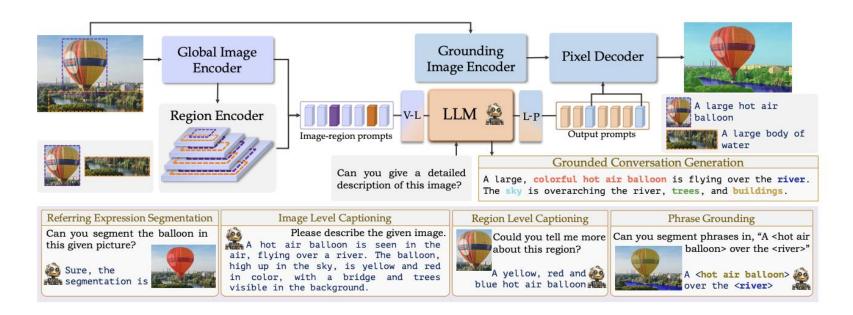
Method	1	refCOC	0	r	efCOCO	refC	refCOCOg		
	val	testA	testB	val	testA	testB	val(U)	test(U)	
CRIS [47]	70.5	73.2	66.1	65.3	68.1	53.7	59.9	60.4	
LAVT [50]	72.7	75.8	68.8	62.1	68.4	55.1	61.2	62.1	
GRES [26]	73.8	76.5	70.2	66.0	71.0	57.7	65.0	66.0	
X-Decoder [63]	-	-	-	-	-	-	64.6	-	
SEEM [64]	-	-	-	-	-	-	65.7	-	
LISA-7B [21]	74.9	79.1	72.3	65.1	70.8	58.1	67.9	70.6	
GLaMM	79.5	83.2	76.9	72.6	78.7	64.6	74.2	74.9	

Table 3. Performance on GCG Task: Metrics include METEOR (M), CIDEr (C), AP50, mIoU, and Mask Recall. LISA\* denotes LISA adapted for GCG. GLaMM† denotes training excluding 1K human annotated images. GLaMM shows better performance.

Table 4. Qualitative Assessment of GLaMM in Referring-Expression Segmentation: Performance across refCOCO, refCOCO+, and refCOCOg in generating accurate segmentation masks based on text-based referring expressions surpasses that of closely related work, including LISA which is specifically designed for this task.



### With Visual Segmentation.

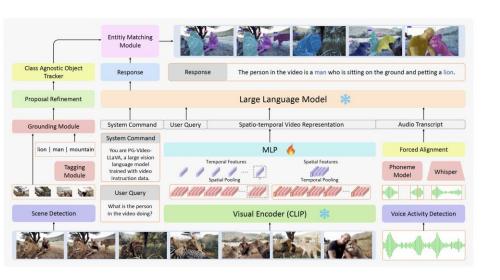


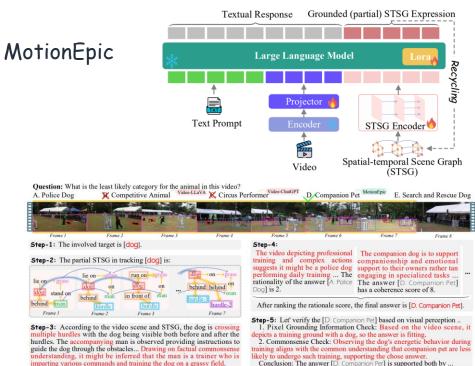
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Video and 3D Fine-Grained MLLM.

PG-Video-LLaVA





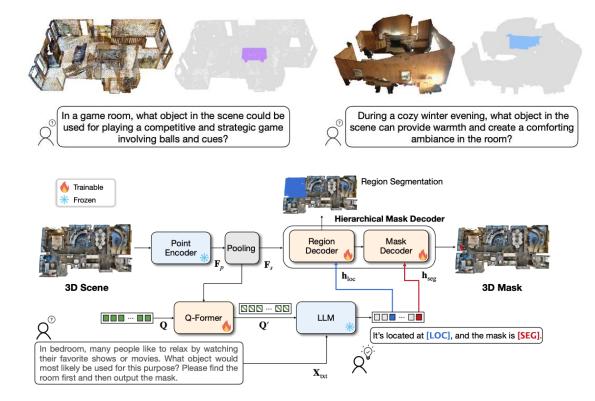
- [1] PG-Video-LLaVA: Pixel Grounding in Large Multimodal Video Models. Arxiv-2023
- [2] Video-of-Thought: Step-by-Step Video Reasoning from Perception to Cognition. Axiv-2024

Video and 3D Fine-Grained MLLM. Video D Revos J Video . Ref-DAVIS17 Refer O Reason Ref-YT-VOS ReVOS F USER: Can you segment the vehicle with highest passenger capacity? Revos R. MeViS 15.5 ASSISTANT: Sure, it is <SEG> 52.7 RefCOCOg ReasonSeg VISA(Ours) gIoU TrackGPT RefCOCO+ Refer O LMPM RefCOCO MTTR VLT - MCN Who will take the baton? It is <SEG> Multi-Model LLM **Object** TFS Tracker  $h_{seq}$ Mask Visual Encoder Decoder

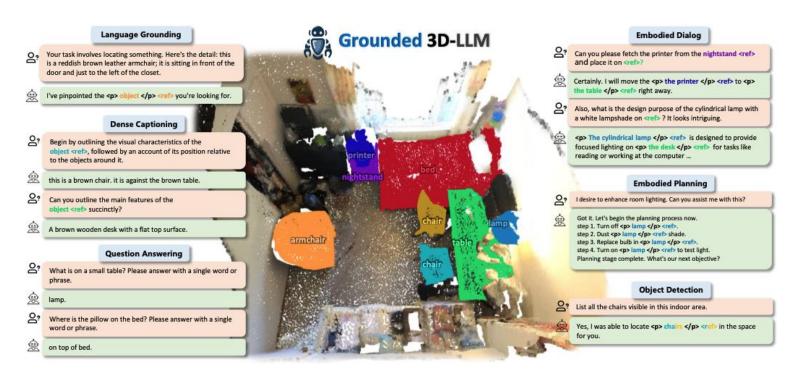
VISA: Reasoning Video Object Segmentation via Large Language Models, arxiv-2024

Video and 3D Fine-Grained MLLM.

Reason3D

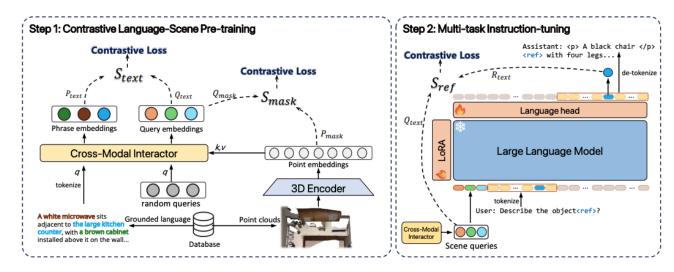


Video and 3D Fine-Grained MLLM.



Video and 3D Fine-Grained MLLM.

Method	LLM	Prompts		Tasks							
	22	Text	Vision	Inst.Seg.	Obj.Det.	Grd.	Point-Grd.	Multi-Obj Grd.	QA	Cap	
PointGroup [37]	Х	-	_	1	1	Х	Х	Х	Х	Х	
Mask3D [62]	X	_	_	/	/	X	×	X	X	X	
Multi3DRef [83]	X	_	_	X	×	/	X	✓	X	X	
BUTD-DETR [36]	X	-	-	×	/	1	×	✓	X	X	
3D-VisTA [88]	X	-	-	X	×	✓	X	×	1	1	
Chat-3D [72]	1	/	Х	Х	Х	Х	Х	Х	1	1	
Chat-3D v2 [33]	/	/	X	×	×	/	×	✓	/	1	
3D-LLM [31]	1	/	X	×	×	1	×	✓	1	1	
LL3DA [11]	1	/	1	X	×	X	X	×	1	1	
Grounded 3D-LLM	1	/	1	1	1	1	1	✓	1	1	



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#### **Overview of Recent Advanced MLLM Designs:**

- 1, More Functionalities:
  - One model For All Language Driven Vision Tasks.
  - Mutual Cross-Task Benefits.
- 2, Long Video Analysis:
  - Temporal Modeling For Extremely Long Video.
  - Efficient Long Context Modeling.
- 3, Multi-Experts Models:
  - Mixture of Experts (MoE) architecture.
  - Better performance and enhanced capacity.

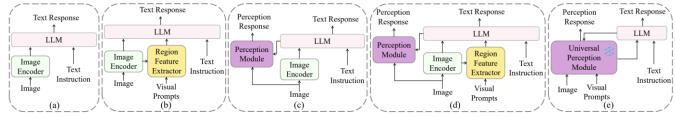
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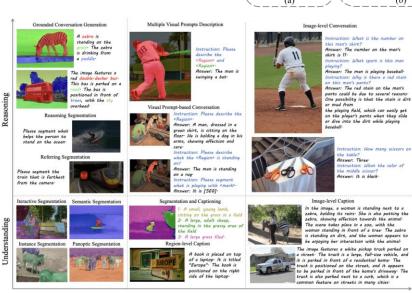
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#### **Unified Architecture**

**OMG-LLaVA** 



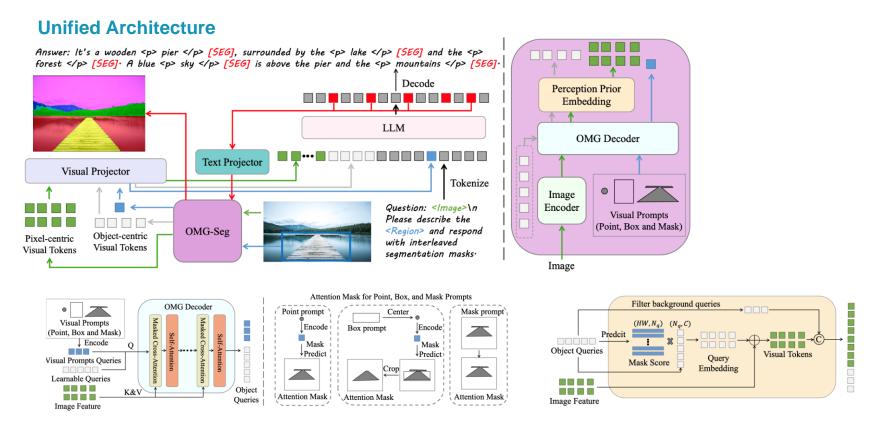


Method	Visual	Ima	age-level	Obje	ct-level		Pixel-	level	
Method	Encoder	Caption	Conversation	Visual Prompts	Caption	Conversation	Universal Seg	RES	GCG
LLAVA [69]	1	<b>√</b>	✓				1		
MiniGPT4 [140]	1	✓	✓						
mPLUG-Owl [116]	1	✓	✓						
LLaMA-Adapter [130]	1	✓	✓						
Mini-Gemini [63]	2	✓	✓						
InternVL 1.5 [18]	1	✓	✓						
VisionLLM [95]	1	✓	✓					✓	
Shikra [13]	1	✓	✓	Point & Box	✓	✓			
Kosmos-2 [80]	1	✓	✓	Box	✓	✓			
GPT4RoI [131]	1	✓	✓	Box	✓	✓			
Ferret [117]	1	✓	✓	Point & Box & Mask	✓	✓			
Osprey [124]	1	✓	✓	Mask	✓	✓			
SPHINX-V [65]	1	✓	✓	Point & Box & Mask	✓	✓			
LISA [47]	2	✓	✓					✓	✓
GLAMM [85]	2	✓	✓	Box	✓	✓		✓	✓
Groundhog [132]	4	✓	✓	Point & Box & Mask	✓	✓		✓	✓
AnyRef [33]	2	✓	✓	Box	✓	✓		✓	
PixelLM [86]	1	✓	✓					✓	
GSVA [107]	2	✓	✓					✓	
Groma [76]	1	✓	✓	Box	✓	✓			
VIP-LLaVA [8]	1	✓	✓	Point & Box & Mask	✓	✓			
PSALM [133]	1			Point & Box & Mask			✓	✓	
LaSagnA [100]	2							✓	
OMG-Seg [56]	1			Point			✓		
OMG-LLaVA	1	✓	✓	Point & Box & Mask	✓	✓	<b>√</b>	✓	<b>√</b>

Pixel-Level Object-Level Image-Level

36







#### Unified Pixel-wise MLLM

+ Vitron





Model	Vision Supporting		Pixel/Regional	Segmenting/	Generating	Editing
	Image	Video	Understanding	Grounding	<b>g</b>	
Flamingo [1]	<b>√</b>	Х	X	X	X	Х
BLIP-2 [45]	<b>✓</b>	X	X	X	X	X
MiniGPT-4 [126]	<b>√</b>	X	X	X	X	X
LLaVA [57]	✓	X	X	X	×	X
GILL [39]	<b>✓</b>	X	X	X	✓	X
Emu [90]	✓	X	X	×	✓	X
MiniGPT-5 [125]	✓	X	X	X	✓	X
DreamLLM [23]	✓	X	X	X	✓	X
GPT4Rol [122]	/	<del>X</del>			x	x
NExT-Chat [118]	✓	X	✓	✓	X	X
MiniGPT-v2 [13]	✓	X	✓	✓	×	X
Shikra [14]	<b>✓</b>	X	✓	✓	X	X
Kosmos-2 [72]	<b>✓</b>	X	✓	✓	X	X
GLaMM [78]	<b>✓</b>	X	✓	✓	X	X
Osprey [117]	✓	X	✓	✓	X	X
PixelLM [79]	✓	X	✓	✓	X	X
LLaVA-Plus [58]	✓	X	X	✓	✓	✓
VideoChat [46]	X	<b>✓</b>	X	Х	Х	X
Video-LLaMA [120]	X	<b>√</b>	X	X	X	X
Video-LLaVA [52]	<b>✓</b>	✓	X	X	X	X
Video-ChatGPT [61]	X	<b>✓</b>	X	X	X	X
GPT4Video [99]	X	<b>✓</b>	X	X	✓	X
PG-Video-LLaVA [67]	<mark>x</mark>				<del>X</del>	<mark>x</mark>
NExT-GPT [104]	<u> </u>	<b>√</b>	Х	X	<u> </u>	X
VITRON (Ours)						



#### Unified Pixel-wise MLLM

Vitron

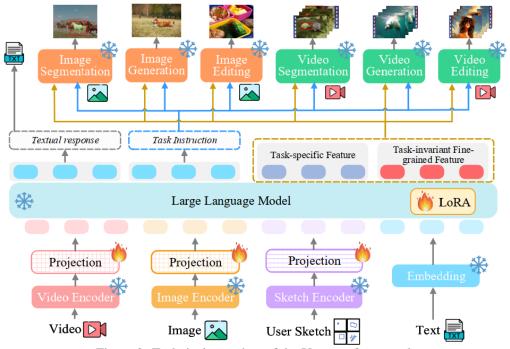
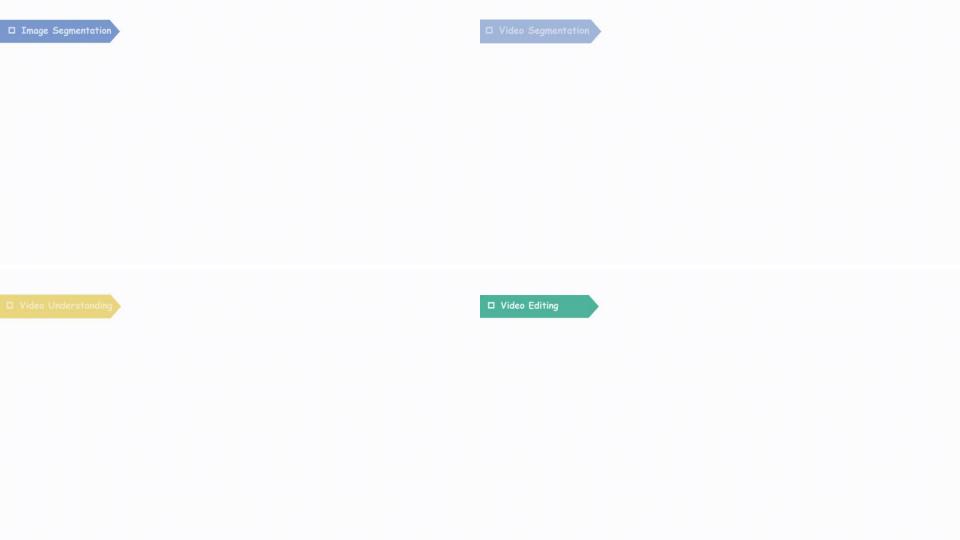
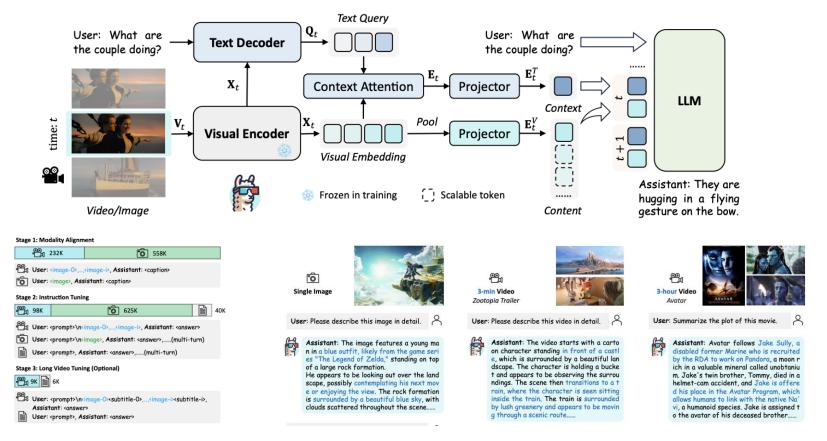


Figure 2: Technical overview of the VITRON framework.



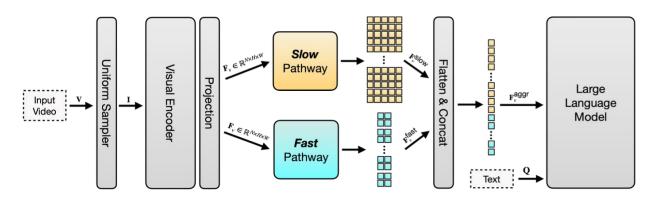
### + Advanced MLLM Design

- × Overview
- × Unified Architecture Designs.
- × MLLM For Long Video Analysis.
- × MLLM With MOE Design.



LLaMA-VID: An Image is Worth 2 Tokens in Large Language Models, arxiv-2023







Question 1: What is happening in this video?

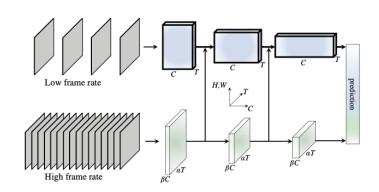
SlowFast-LLaVA-7B: The video depicts a person preparing a cup of coffee, which is a common activity in the morning or during breaks. The coffee machine is a modern, sleek design with a digital display. The kitchen is well-equipped with various appliances and utensils. There's a sink with a faucet, a dishwasher, and a refrigerator. On the countertop, there are several items including a bowl, a spoon, and a cup. The overall content of the video is a snapshot of everyday life, capturing the simple yet essential act of making coffee in a home setting.

Question 2: When does the person wash the portafilter?

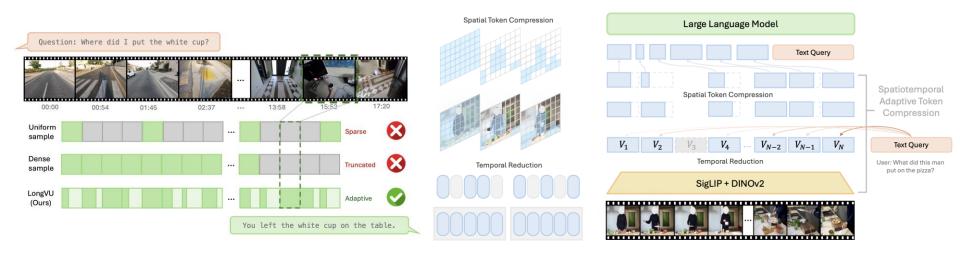
SlowFast-LLaVA-7B: The person washes the portafilter at the end of the video, after preparing the coffee.

Question 3: Does this person open the refrigerator?

SlowFast-LLaVA-7B: No, the person in the video does not open the refrigerator.



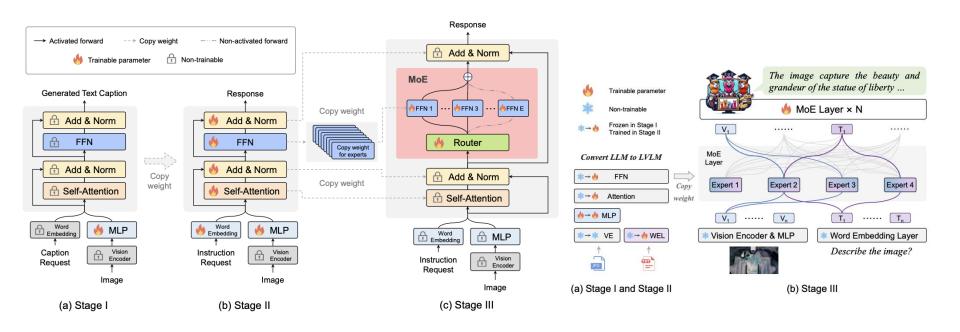


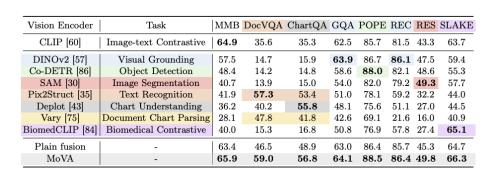


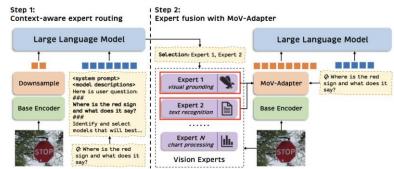
$$\mathbf{Top}_{N_h}\left(\frac{1}{H_hW_hL_q}\sum_{h,w,l}\mathcal{F}(V)Q^T\right),\quad N_h=\max\left(0,\frac{L_{\max}-L_q-TH_lW_l}{H_hW_h-H_lW_l}\right),$$

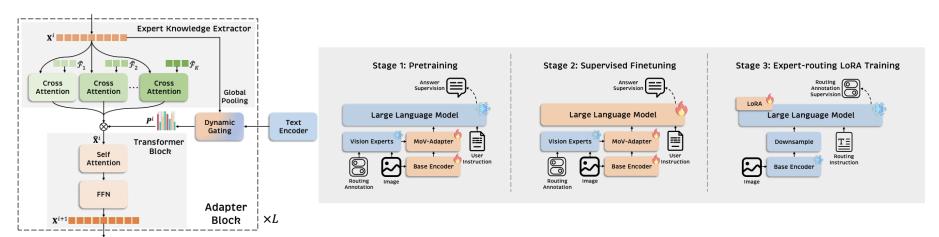
### + Advanced MLLM Design

- × Overview
- × Unified Architecture Designs.
- × MLLM For Long Video Analysis.
- × MLLM With MOE Design.









## MLLM Functionality& Advance

### → Fine-Grained MLLM Design

- With Visual Grounding.
- × With Visual Segmentation.
- × Video and 3D Fine-Grained MLLM.

### + Advanced MLLM Design

- Unified Architecture Designs.
- × MLLM For Long Video Analysis.
- × MLLM With MOE Design.

Fine-Grained Understanding.

Stronger Features and Capacities.

### MLLM Functionality& Advance

#### **Future Direction:**

- 1, Scaling MLLM features More.
- 2, Novel MoE operators designed for MLLMs.
- 3, Single Transformer Architecture. Eg: unify image generation and text generation in one model.
- 4, Long Video Grounding, Chat and Tracking in One Model.

# Thanks!

